

Final Control Components

Electric Actuators

Free from Requirements of Instrument Air Systems

Control Valves with STEPTOP Electric Actuators

Control Valves with STEPTOP Electric Actuators

Application Examples Pulp & Paper Mill



This symbol identifies those products which contains less than the maximum levels of the 10 restricted substances specified by the RoHS Directive.

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Compact Linear Motion Electric Actuators

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Electric Actuators **PSN** Series

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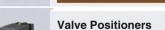
Rotary Motion Electric Actuator MRP10













MEX Series

See Page **26**



Manual Loading Stations

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Product videos are on our website!

STEPTOP Electric Actuator

Revolution of Electric Control Valves

STEPTOP Electric Actuator

1/1000 Resolution Demo Kit

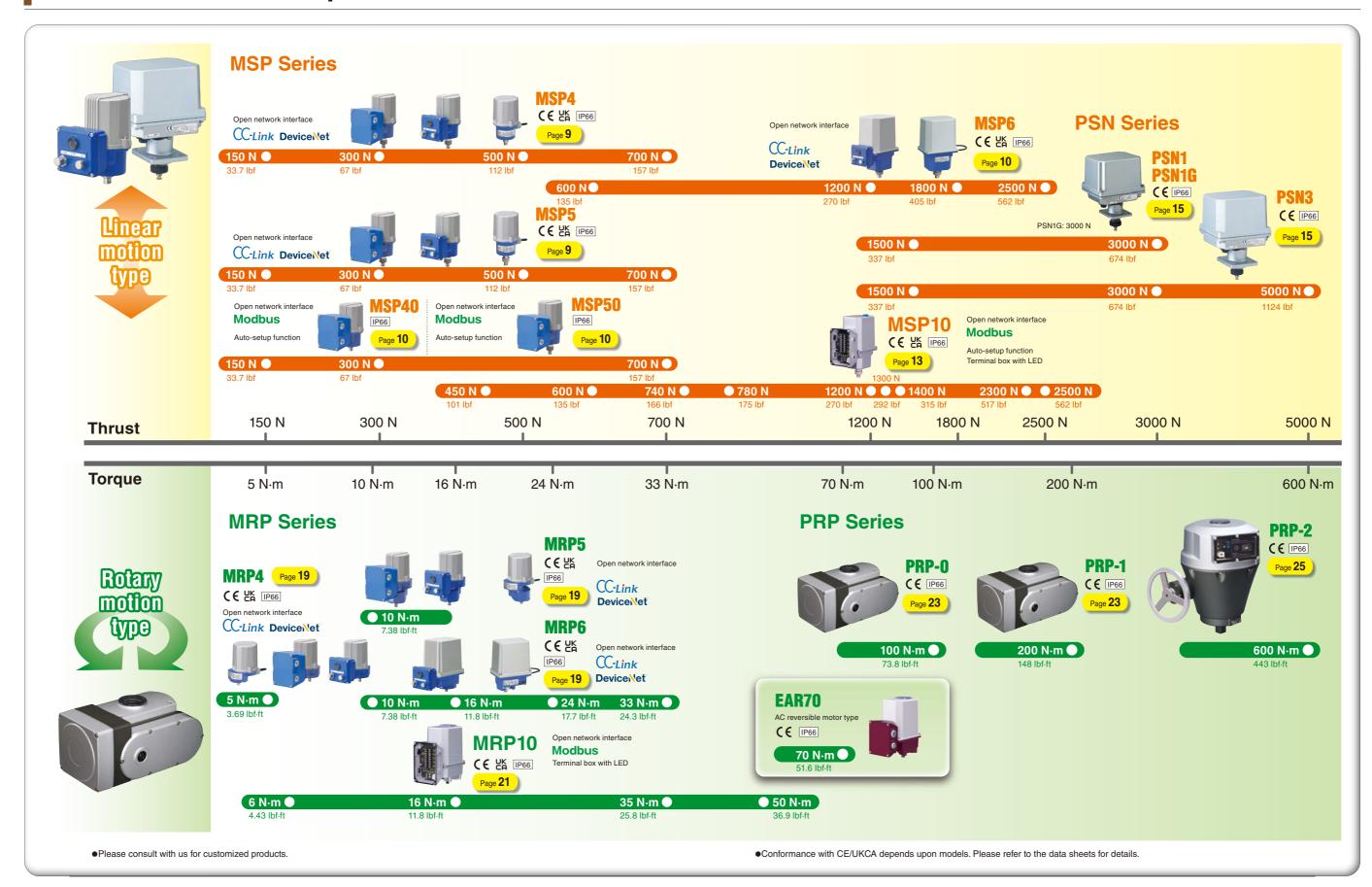
Please visit our website: https://www.mgco.jp/video_e/index.html





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Electric Actuators Lineup



MSP

MSP10

Series

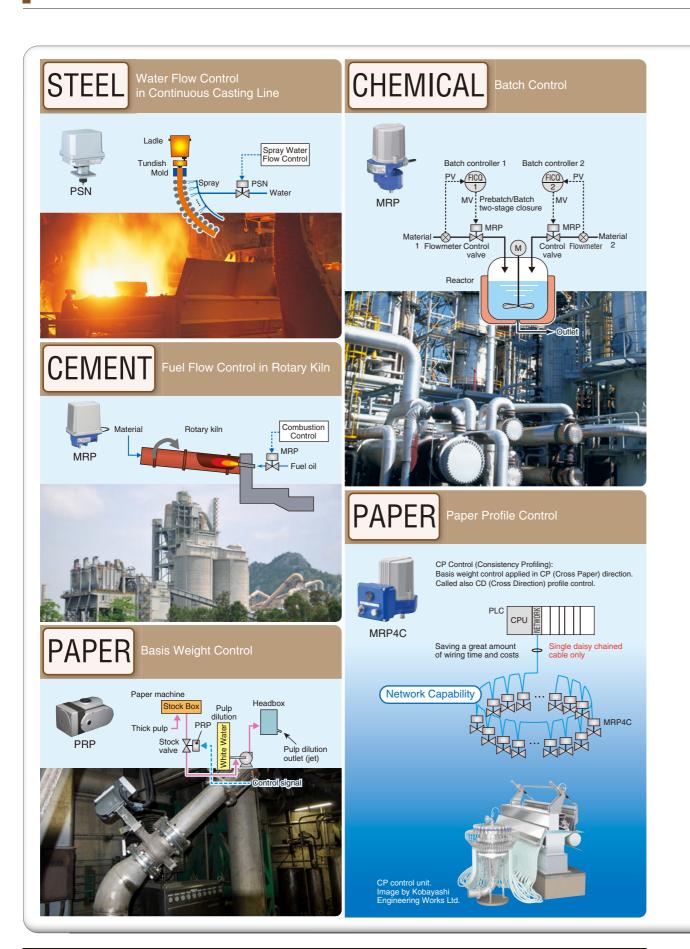
Positioners MEX Series

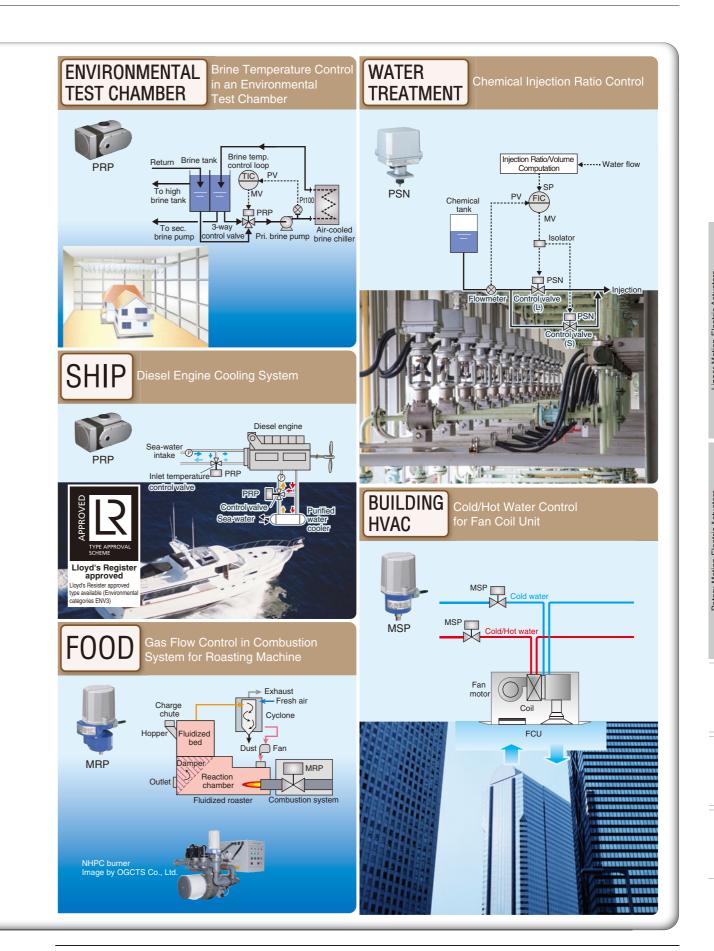
Manual Loading

Positioners

MEX Series

Application Examples in Various Demanding Process Fields





MEX Series

MEX Series

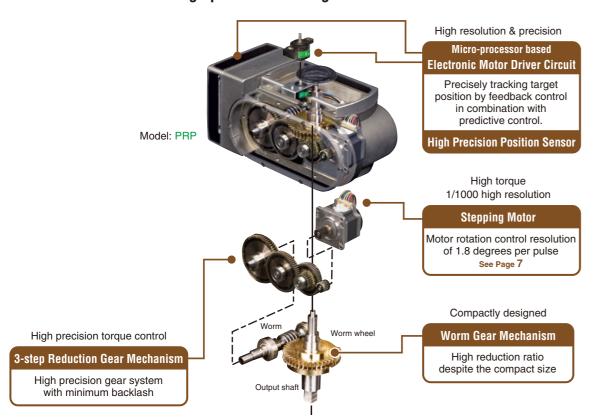
Loading

Electric valves can reduce the equipment cost to $1/5^{*1}$ and

control valve does The pneumatic control **ELECTRIC** valve requires complicated equipment and consumes PNEUMATIC equipment, and plenty of power Control signal Control signal 4 - 20 mA DC 4 - 20 mA DC or open network (IP) 20 - 100 kPa No Need instrument air system nor ancillary equipment! Power source Compressor Aftercooler Air Prefilter Mist Dryers After receiver separator filter A compressor Equipment cost \$\preceq 1/5*1 ntails equipment costs Instrument air system and ancillary Energy consumption ↓ 1/10* as well as troublesome equipment can be eliminated by maintenance work! Vhat is more, it results i Only standby power switching pneumatic valves to igh electricity bills! the control loop is in a electric ones.

*2. Maximum power consumption: 240 VA Standby power: 20 VA

Mechanism that achieves high precision and high resolution control



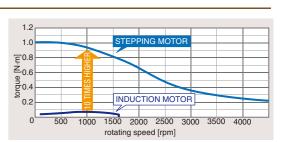
the energy consumption to $1/10^{*1}$ compared from those of pneumatic valves.

■ Features of Stepping Motor

Comparing to an induction motor

A stepping motor has the following advantages compared to an induction motor. It is most suitable as an actuating drive for small mechanisms including control valves.

- High torque for small size (approx. 10 times greater than an induction motor of the same mass)
- High torque at startup; with little torque variation during acceleration
- · Variable rotating speed
- Rotating speed unaffected by load changes
- · High precision positioning by acceleration/deceleration control
- Unaffected by voltage or frequency variations by the power source

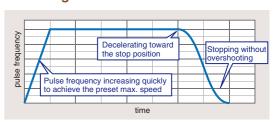


Predictive control enabling the motor to stop without overshooting

Basic rotating step per pulse of the two-phase stepping motor employed by the electric actuators is 1.8 degrees, thus requiring 200 pulses to complete a full

The exact number of pulses is controlled by a micro-processor.

The "Predictive Control" employed as a part of its control algorithm enables the actuator to smoothly stop at an exact position (angle) without overshooting.



Mechanism of Stepping Motor

The below illustrations show cross section images of a stepping motor, called also "stepper motor" or "step motor."

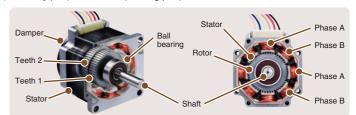
The stepping motor consists of two major components: a stator (stationary part) and a rotor (rotating part).

The rotor is a permanent magnetic rotating shaft,

surrounded by eight electromagnets or coils of two phases (A and B).

Each electromagnet is energized in turn, attracting and repulsing the rotor to rotate its shaft.

The motor shaft is connected to a damper that enhances the torque characteristics of the motor at high speed.



How Stepping Motor Works

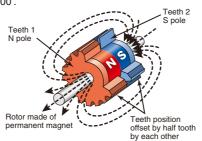
1/1000 Resolution

The N pole and S pole toothed gears are engaged with an offset of half tooth. The bottom of a N pole tooth is aligned with the top of a S pole tooth.

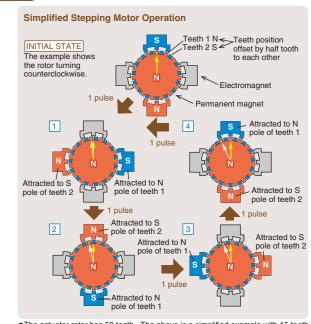
Each pulse moves the shaft by a quarter (1/4) tooth pitch while the N pole teeth and the S pole teeth are attracted and repulsed in turn Each of those rotations is called a "step".

The motor has 50 teeth around the wheel, turning 1.8 degrees per step, requiring 200 pulses to make a complete rotation with an integer number of steps. In this way the motor can be turned by a precise mechanical angle in high resolution.

The motor shaft rotates more than 100 times while the actuator travels the entire stroke/span. The calculated resolution is greater than 1/20000°.



* The nominal resolution described in the actuator data sheet is 1/1000 considering additional influencing factors such as the accuracy of the position detecting sensor, backlash of the reducing gear mechanism.



The actuator rotor has 50 teeth. The above is a simplified example with 15 teeth

MSP10

Series

Positioners MEX Series

Manual Loading

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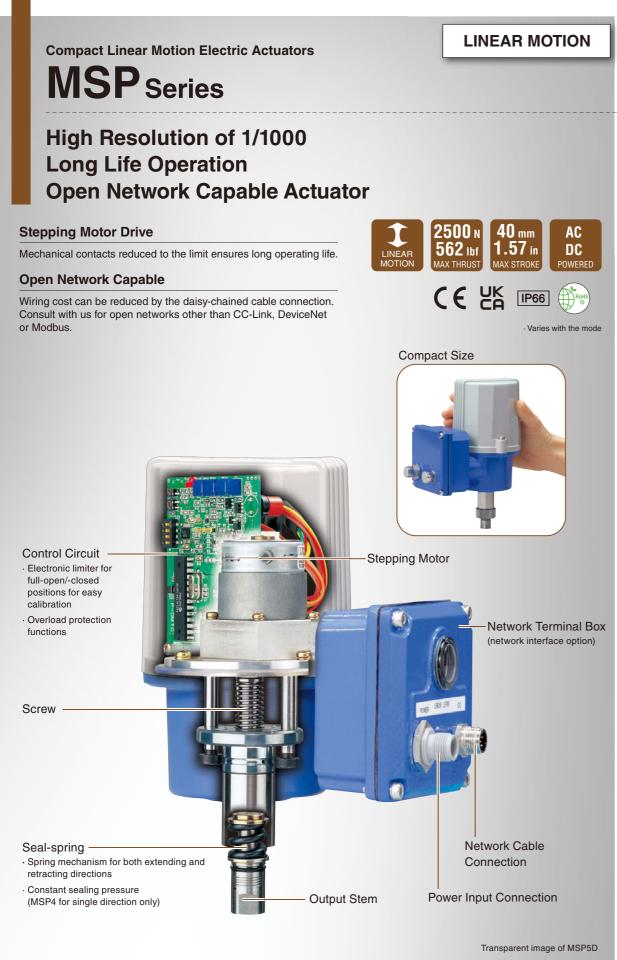
MEX Series

Series

MEX Series

Manual

Loading



Linear Motion MSP Series

Analog I/O Type MSP Common Specifications

Input signal : 4 - 20 mA or 1 - 5 V DC

Power input

: Option (MSP4, MSP5)

: 24 V AC (only for MSP6, not selectable for CE) 100 - 120 V AC (not selectable for CE and UKCA) 200 - 240 V AC (not selectable for CE and UKCA) 24 V DC

: Limit switch contact (Option) Full-open/-closed

: Dry contact inputs (Option) Forced open/close

Manual operation function

Degree of protection

Wiring : Cable, terminal box (Option)

Drive : Stepping motor : 1 - 5 V DC (Not isolated)

Operating temperature : -5 to +55°C (23 to 131°F) · 0.5 G (4.9 m/s²) max

Open Network Capable Type MSP Common Specifications

: 24 V DC Power input

: IP66, IP67 (MSPxD connector)

Degree of protection

Wiring conduit : Microconnector (MSP4C, MSP5C, MSP6C, MSP4D, MSP5D, MSP6D)

Drive : Stepping motor Position : Potentiometer

Operating : -5 to +55°C (23 to 131°F)

Vibration : 0.5 G (4.9 m/s²) max.

Vibration		: 0.5 G (4.9	m/s²) max.						
		MSP Series							
External View		MSP4	MSP4	C2	MSP4C MSP4D	MSP5	MS	P5C2	MSP5C MSP5D
	Analog Type	MSP4	CE LA			MSP5	CE LA		
	Network Capable Type	MSP4C2 MSP4C	CC-Link	MSP4D	DeviceNet C € IP66 (IP67 connector)	MSP5C2 MSP5C	CC-Link	MSP5D	Device et
Operation Time @ 10 mm		9 sec / 300 N (6/ lpt)			sec. / 500 N (112 lbf) sec. / 700 N (157 lbf) 5 sec. / 150 N (9 sec. / 300 N (18 sec. / 700 N (N (67 lbf)	24 sec. /	300 N (67 lbf) 500 N (112 lbf) 700 N (157 lbf)
Stroke		15 mm (0.59")				20 mm (0.79")			
Approx. We network capable	٠ ا	1.4 kg [3.09 lb] (1.5 kg [3.3 lb], 1.8 kg [4.0 lb] (MSPxC2))							
Resolutio	n	1/1000 or 0.015 mm, whichever is greater, with 0.1 % deadband setting							
External Dimensions ^{*1} (unit: mm [inch])		MSPxC, MSPxD	85 [3.35]	43 [1.69]16 [.63]	90 (3.54)	MSxC2 42 (1.65) 118 (4.65) (73 (2.87)) (90) (90) (10)			
		90 (3.64) **2 **1.34 **1.15.35 **1.134 **1.15.35 **1.134 **1.15.35 **1.134 **1.15.35 **1.134 **1.15.35 **1.134 **1.15.35 **1.134 **1.15.35 **1.134 **1.15.35 **1.134 **1.135 **1.134 **1.135 **1.134 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135 **1.135				96 (3.78) [22,889] WAX 20 (1.14) [2.69] WAX 30 (1.14) [2.69] 12.00 12.00 12.00 12.00 12.00 13.00 14.00 15.00 16.00 16.00 17.00 17.00 18.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 19.00 1			
			*29 [1.14] ma	ax. for the stroke	5 – 10 mm	*29 [1.14] max. for the stroke 5 – 10 mm			

*1. Dimensions for network capable types.
*2. 50 [1.97] max. for MSP5C, MSP5D (40 [1.57] max. for 5-10 mm stroke)

*3. 50 [1.97] max. for MSP5C2 (40 [1.57] max. for 5-10 mm stroke)

Series

Positioners MEX Series

Manual Loading

Series

MRP10

Series

Linear Motion MSP Series

Modbus Type with Auto-Setup Function Common Specifications

Input signal : 4 - 20 mA or 1 - 5 V DC Power input : 24 V DC

Degree of protection Wiring conduit : Stepping motor

Position detection : Conductive potentiometer

Position output : 4 - 20 mA DC or 20 - 4 mA DC (non-isolated) 1 - 5 V DC or 5 - 1 V DC (non-isolated)

Alarm output (triggered when the output stem is locked)

: Photo MOSFET relay Output type Rated load : 160 V 150 mA AC/DC at peak

 ON resistance : 8 Ω max. Leakage current during : 2 µA max. opening/closing

: -5 to +55°C (23 to 131°F) Operating temperature

Vibration resistance (Sweep endurance test (IEC 61298-3 compliant))

 Acceleration : 19.6 m/s2 (2 G)

MSP Series External View C€ EK MSP6 IP66 Modbus Type with Auto-Setup Modbus Type with Auto-Setup Function Common Specifications Function Common Specifications Model No. CC-Link DeviceNet* MSP40 MSP50 MSP6C MSP6D **(€** IP66 € 9 sec. / 600 N (125 lbf) Operation Time 5 sec. / 600 N (135 lbf) 5 sec. / 150 N (33.5 lbf) 5 sec. / 150 N (33.5 lbf) 18 sec. / 1,200 N (270 lbf) (10 mm/ 8 sec. / 1200 N (270 lbf) 9 sec. / 300 N (67 lbf) 9 sec. / 300 N (67 lbf) 24 sec. / 1,800 N (405 lbf) Max. Thrust) 15 sec. / 2500 N (562 lbf) 18 sec. / 700 N (157 lbf) 18 sec. / 700 N (157 lbf) 36 sec. / 2,500 N (562 lbf) Stroke 40 mm (1.57") 15 mm (0.59") 20 mm (0.79") Approx. Weight 3.6 kg [7.9lb] (2.8 kg [6.17 lb]) 1.9 kg (4.2 lb) 1.9 kg (4.2 lb) (Network capable type 1/1000 or 0.015 mm (MSP6, MSP6D 0.02 mm), whichever is greater, with 0.1 % deadband setting Resolution MSP6x Dimensions* (Unit: mm [inch] 36 [1.42] dia. The dimension in () is when the stroke is set to 5 to 10 mm The dimension in () is when the stroke is set *58 [2.28] max, for the stroke 10 - 20 mm Yoke set Programming Unit Accessory (€ ∰ Model: PU-2A Model: YSS

AUTO-SETUP FUNCTION: MSP40 / MRP50

Auto-setup is the function for automatically adjusting the full-closed/-open positions and the seal spring pressure when the actuator is mounted on a valve.

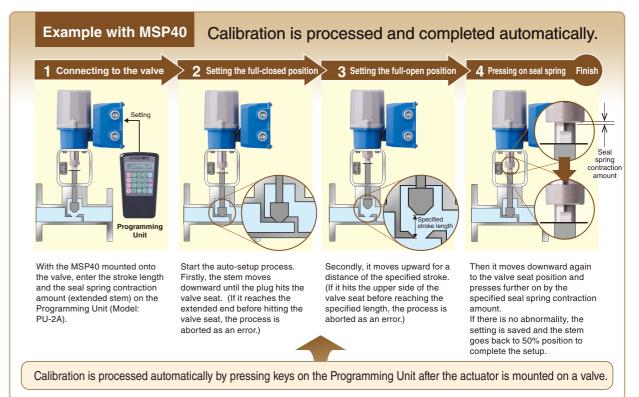


By entering the valve stroke length and the necessary seal spring contraction amount using the Programming Unit (Model: PU-2A) or via Modbus communication, adjustments are performed automatically, saving manual calibrations and reducing commissioning time.

You do not have to have the Programming Unit to use the auto-setup function.

If you do not have the Programming Unit or do not wish to use Modbus communication, all you have to do is filling values of the valve stroke length and the necessary seal pressure in Ordering Information Sheet when you order the product. Our factory will proceed with all settings for you for free of charge.

Auto-setup can be also performed by manipulating DIP switches equipped on the actuator unit.



MSP10

PSN

Series

Series

Positioners MEX Series

Manual Loading

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MEX Series

^{*1.} Dimensions for network capable types.

Series

MEX Series

Loading

Linear Motion Electric Actuator

LINEAR MOTION

MSP10

High resolution 1/1000, Modbus communication, Easy installation and maintenance

Auto-setup Function

The time and effort required to adjust the valve opening is

Those for maintenance work can be also saved.

Modbus Communication

Directly connectable to PLC/PC network Actuators' operation data can be accumulated while in the normal operation.

Convenient Terminal Box

Terminal blocks, switches, buttons and LEDs are all housed in the terminal box for the ease of installation and maintenance.



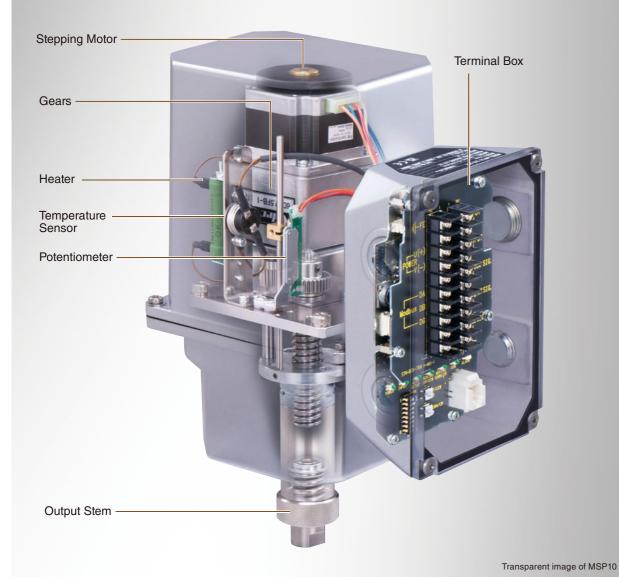




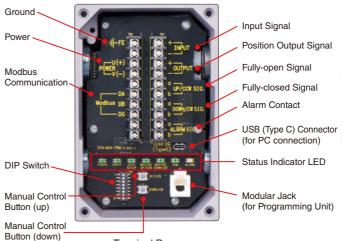




Varies with the model



All Control Circuits Housed in the Terminal Box



1. Easy wiring

The terminal box is separate from the main unit to make wiring work easier.

2. Operation can be checked at a glance

LEDs for operating status indication can be checked through the rugged, transparent polycarbonate cover.

3. Easy parameter setting

Various parameters can be set with DIP switches or by using the Programming Unit (PU-2A) connected to the modular jack in the terminal box, without opening the cover of the main actuator body. In addition, parameters can also be set from a PC using the configurator software (Model: STCFG).1

Linear Motion MSP10

Main Specifications

■GENERAL SPECIFICATIONS

Degree of protection

: G 1/2 female thread and G 3/4 female Wiring conduits thread (total four)

Drive Stepping motor Position detection

Conductive potentiometer

Power voltage or I/O signal to retract/UP signal position to extend/DOWN signal position to alarm signal to Modbus communication to metallic housing

Protective functions

· Automatically stops when thrust at lock (abnormal thrust increase)

· A heater is incorporated to use under cold areas.

■MODBUS COMMUNICATION

Communication : Half-duplex, asynchronous, no procedure : TIA/EIA-485-A compatible Standard

Transmission distance: 500 meters max.

■INPUT SPECIFICATIONS

: 4 - 20 mA DC or 20 - 4 mA DC (non-isolated) Input signal

1 - 5 V DC or 5 - 1 V DC (non-isolated) ■OUTPUT SPECIFICATIONS

: 4 - 20 mA DC or 20 - 4 mA DC (non-isolated) Output signal 1 - 5 V DC or 5 - 1 V DC (non-isolated)

Alarm output (triggered when the output stem is locked), retract/UP signal position, extend/DOWN signal position:

Photo MOSFET relay ■INSTALLATION

Power input

: 24 V DC

Operating temperature : -15 to +66°C (5 to 150.8°F) (No direct sunlight, radiant heat or heat transfer.)

Vibration resistance (Sweep endurance test (IEC 61298-3 compliant))

19.6 m/s² (2 G) Acceleration

Mounting orientation : DO NOT mount upside-down

: 4 kg (8.820 lb) Approx. weight

	MSP10			
		External Dimensions (Unit: mm [inch])		
External View		145 [5.71] 72.5 [2.85] 64.5 [2.54] 91 108.5 [4.27]		
Model No.	MSP10 C€ CK IP66 €	2-G 3/4		
Output Stem Operation Distance	20mm [.79"] (adjustable to 10mm [.39"]) Max. stroke ≤ 20.0mm [.79"] or 40mm [1.57"] (adjustable to 20mm [.79"]) Max. stroke ≤ 40.0mm [1.57"]	136.5 [5.37]		
Operation Time ^{*2} @ 20 mm [.79"] /Thrust (Thrust at Lock)	3.2 sec./450N (500N) 4 sec./600N (620N) 5.7 sec./740N (790N) 7.4 sec./780N (790N) 7 sec./1200N (1500N) 8.4 sec./1300N (1500N) 10 sec./1400N (1500N) 10 sec./1400N (1500N) 10 sec./2500N (2700N) 10 sec./2500N (2700N) 10 sec./2500N (2700N) 10 sec./2500N (2700N)	2-G 1/2 55-0.1 dia.		

*1. The configurator software (Model: STCFG) can be downloaded for free from our web site.

*2. Operation time can be changed on site using the configuration software (Model: STCFG) or the Programming Unit (Model: PU-2A). Be sure to confirm the data sheet

Series

Series

Positioners

MEX Series

Loading

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Series

MEX Series

Loading



Linear Motion PSN Series

PSN Series Common Specifications

: 4 - 20 mA or 1 - 5 V DC Input signal

: 100 - 120 V AC (not selectable for CE) 200 - 240 V AC 24 V DC Power input

Degree of protection: IP66

: G 1/2 female thread (two), G 3/4 female thread (two) Wiring conduits

: Stepping motor Position detection: Brushless angle sensor

Position signal : 4 - 20 mA DC $1 \le 2 \text{ G } (19.6 \text{ m/s}^2)$

	d 6/4 female timeda (two)			
	PSN Series			
External View				
Model No.	PSN1 (€ 1P66	PSN3 (€ IP66 €		
Stroke	0 to 40 mm (0" to 1.57")	0 to 60 mm (0" to 2.36")		
Max. Thrust	3000N	5000N		
Opening/closing speed adjustment	0.30 – 5.65 mm/s	0.22 – 4.02 mm/s		
Operating temperature	-25 to +55°C (-13 to +131°F)	-15 to +55°C (5 to 131°F)		
Approx. Weight	5.9 kg (13.0 lb)	8.9 kg (18.7 lb)		
Resolution	0.04 mm	0.06 mm		
External Dimensions (Unit: mm [inch])	MANUAL OPERATIO STEM, 8 [31] sq. MANUAL OPERATIO STEM, 8 [31] sq. VOKE SURFACE	200 [7.87] 110 [4.33] 90 [3.54] 110 [4.33] 90 [3.54] 110 [4.33] 90 [3.54] 110 [4.33] 90 [3.54] 110 [4.33] 90 [3.54] 110 [4.33] 90 [3.54] 110 [4.33] 90 [3.54] 110 [4.33] 90 [3.54] 110 [4.33] 90 [3.54] 110 [4.33] 90 [3.54] 110 [4.33] 90 [3.54] 110 [4.33] 90 [3.54] 110 [4.33] 90 [3.54] 110 [4.33] 90 [3.54] 110 [4.33] 90 [3.54] 110 [4.33] 90 [3.54] 110 [4.33] 90 [3.54]		
_	Manual Operation Spanner Model: HPSN2			
Accessory	Battery Model: PSN-BAT			
	Programming Unit Model: PU-2A (€			

Series

Positioners MEX Series

Manual Loading

www.mgco.jp www.mgco.jp Series

MSP10

MRP10

Series

MEX Series

Loading

Stations

Linear Motion PSN Series

PSN1G Specifications

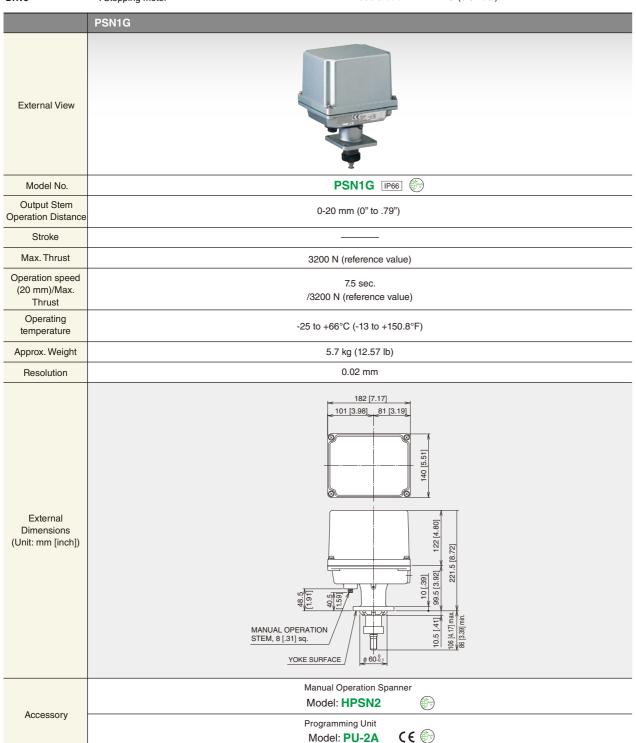
Input signal : 4 - 20 mA DC : 24 V DC Power input Degree of protection: IP66

Wiring conduits : G 1/2 female thread (two)

Drive : Stepping motor Manual operation : 4 - 20 mA DC

Operating temperature: -25 to +66°C (-13 to +150.8°F) Vibration resistance (Sweep endurance test)

: 1 G (9.8 m/s²) · Acceleration



Video Library



Control Valves with STEPTOP Electric Actuators

Application Examples Pulp & Paper Mill

This video introduces our STEPTOP electric actuators, with a focus on application examples in pulp and paper mills.

https://www.mgco.jp/video_e/steptop_application/





Free from Requirements of Instrument Air Systems **Control Valves with STEPTOP Electric Actuators**

This video introduces common air systems and how electric control valves with STEPTOP actuators are revolutionizing the control valve industry.

https://www.mgco.jp/video_e/e_actuators_steptop/



STEPTOP Electric Actuator Revolution of Electric Control Valves

The video compares the control result of an electric control valve with that of a pneumatic control valve, both installed in an actual flow control loop.

https://www.mgco.jp/video_e/e_actuators/index.html





STEPTOP Electric Actuator 1/1000 Resolution Demo Kit

The 1/1000 Resolution Demo Kit demonstrates STEPTOP's performance at a glance and shows the innovation in electric control valve technology.

https://www.mgco.jp/video_e/actuators/index.html

Collaboration Maps

The "Map" brochures explain the functions and applications of electric actuators with "manga" style illustrations.

ASAHI YUKIZAI CORPORATION



Japan

Dalian Shuntian Xingda Special Valve Co., Ltd.



JDV CONTROL VALVES CO., LTD.



Taiwan

TOKO VALEX CO., LTD.



Japan

Wuxi KELK Apparatus & Valve CO., LTD.



WYECO AUTO VALVES CO., LTD.



Taiwan

MSP10

Series

Positioners MEX Series

Manual Loading

Series

MEX Series

Loading

ROTARY MOTION Compact Rotary Motion Electric Actuators MRP Series High Resolution of 1/1000 **Long Life Operation Open Network Capable Actuator** Compact Size **Stepping Motor Drive** Mechanical contacts reduced to the limit ensures long operating life. **Open Network Capable** Wiring cost can be reduced by the daisy-chained cable connection. Consult with us for open networks other than CC-Link or DeviceNet. DC Stepping Motor Network Potentiometer **Terminal Box** Network communication circuits are incorporated. (network interface option) Terminal Block Station No. Setting

Output Stem

Transparent image of MRP5C2

Rotary Motion MRP Series

Analog I/O Type MRP Common Specifications

: 4 - 20 mA or 1 - 5 V DC Input signal

: 100 - 120 V AC (Not selectable for CE and UKCA) 200 - 240 V AC (Not selectable for CE and UKCA) Power input

Degree of protection

Wiring Cable

Terminal box (Option) Drive Stepping motor

Position detection : 1 - 5 V DC (not isolated)

Position output : Limit switch contact (Option) Full-open / -closed

: Dry contact (Option) Forced open/close

Operating temperature : -5 to +55°C (23 to 131°F)

Open Network Capable Type MRP Common Specifications

: 24 V DC Power input

Degree of protection : IP66 IP67 (MRPxD connector)

Wiring conduits : Microconnector (MRP4C, MRP5C, MRP6C, MRP4D, MRP5D, MRP6D)

With terminal block (MRP4C2, MRP5C2)

: Stepping motor Position detection : Potentiometer

: -5 to +55°C (23 to 131°F) Operating temperature

Vibration : 0.5 G (4.9 m/s²) max

Vibration : 0.5 G (4.9 m/s²) max.

MRP Series External View MRP4 MRP5 MRP6 Model No. CC-Link CC-Link CC-Link DeviceNet Device/\et Device Net MRP5C2 MRP5D MRP6C MRP4D MRP4C2 MRP6D MRP4C **(€** IP66 MRP5C C € [IP66] **C €** [IP66] 7 sec. /10 N·m 4 sec. /10 N·m (7.38 lbf·ft) (7.38 lbf-ft) 7 sec. /5 N·m 14 sec. /16 N·m 7 sec. /16 N·m Operation Time 13 sec. /10 N·m 22 sec. /10 N·m (3.69 lbf-ft) 12 sec. /5 N·m (11.8 lbf-ft) (11.8 lbf-ft) (90°) /Torque 13 sec. /5 N·m (3.69 lbf·ft) (7.38 lbf-ft) (7.38 lbf-ft) 18 sec. /24 N·m 13 sec. /33 N·m (3.69 lbf-ft) 17.7 lbf-ft) (24.3 lbf-ft) 27 sec. /33 N·m 24.3 lbf-ft) Span 45 to 90 degrees, 90 to 180 degrees 45 to 90 degrees 45 to 90 degrees, 90 to 180 degrees Approx. Weight I.3 kg [2.87 lb] (1.4 kg [3.1 lb], 1.7 kg [3.7 lb] (MRP4C2)) | 1.7 kg [3.7 lb] (1.8 kg [4.0 lb], 2.0 kg [4.4 lb] MRP5C2)) 2.8 kg (3.0 kg) 1/1000 or 0.09°, whichever is greater, with 0.1 % deadband setting Resolution MRP4C, MRP4D External Dimensions* (Unit: mm [inch])

*1. Applicable to network capable type

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Manual Loading

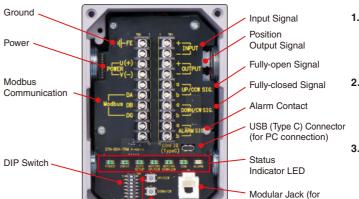
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Zero/Span Adjustments Forced Control Buttons

MEX Series

Loading

All Control Circuits Housed in the Terminal Box **ROTARY MOTION**



The terminal box is separate from the main unit to make wiring work easier.

2. Operation can be checked at a glance

LEDs for operating status indication can be checked through the rugged, transparent polycarbonate cover.

3. Easy parameter setting

Various parameters can be set with DIP switches or by using the Programming Unit (PU-2A) connected to the modular jack in the terminal box, without opening the cover of the main actuator body. In addition, parameters can also be set from a PC using the configurator software (Model: STCFG)."2

Rotary Motion MRP10

Main Specifications

Manual Control Button

Manual Control Button (clockwise turn)

(counterclockwise turn)

■GENERAL SPECIFICATIONS

Degree of protection

Wiring conduits

: G 1/2 female thread and G 3/4 female

thread (total four)

Terminal Box

Position detection : Conductive potentiometer

Isolation

Power voltage or I/O signal to full-open signal position to full-close signal position to alarm signal to Modbus communication to

Protective functions

· Automatically stops when torque at lock

· A heater is incorporated to use under cold areas.

■MODBUS COMMUNICATION

Half-duplex, asynchronous, no procedure

Transmission distance: 500 meters max.

Standard : TIA/EIA-485-A compatible

■INPUT SPECIFICATIONS

: 4 - 20 mA DC or 20 - 4 mA DC (non-isolated)

1 - 5 V DC or 5 - 1 V DC (non-isolated)

■OUTPUT SPECIFICATIONS

: 4 - 20 mA DC or 20 - 4 mA DC (non-isolated) 1 - 5 V DC or 5 - 1 V DC (non-isolated)

Alarm output (triggered when the output stem is locked), Full-open

signal, full-close signal: Photo MOSFET relay

■INSTALLATION

Programming Unit)

: 24 V DC

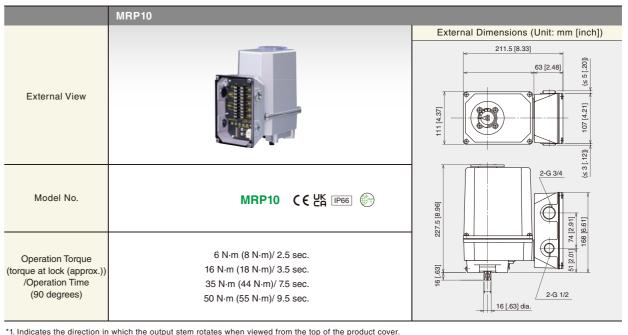
Operating temperature : -25 to +66°C (-13 to 150.8°F)

(No direct sunlight, radiant heat or heat transfer.) Vibration resistance (Sweep endurance test (IEC 61298-3 compliant))

19.6 m/s² (2 G)

Mounting orientation : DO NOT mount upside-down

: 4.4 kg (8.820 lb)



- *2.The configurator software (Model: STCFG) can be downloaded for free from our web site.



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Manual Loading

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ROTARY MOTION Rotary Motion Electric Actuators PRP Series High resolution 1/1000, High speed operation 8.5 sec./90°, Freely selectable opening/closing speed Long Life and High Precision Lloyd's Register Type Approval Stepping motor drive realizes long life and high precision control. Lloyd's Resister approved type available (Environmental categories ENV3) **IP66** IP66 degree of protection **Open Network Capable** Contact us for details. compliant with ISO 5211/Table 1, 2 F7 **((IP66**) Potentiometer (conductive plastic) Long Life and High Precision Stepper Motor Worm Wheel Worm Gear Angle Indicator The drive section employs a stepping motor, which ensures long life because of no mechanical contact, and high precision control operated by the number of pulses. Long life and high precision is balanced. Ball Bearing and Reduction Gears (Another bearing is at the rear side of the eduction gears.) Backup Battery for Failsafe Operation Transparent image of PRP-0, -1

RJ-45 Connector For programming with PU-2A hand held programmer

User-configurable items: Full-closed/open position

- Opening/closing speed Closed/open side limiter
- Full-closed/open signal
- Split range and point

- Restart limiting timer

High Speed Opening/Closing 8.5 to 125 sec./90°

Manual Operation Stem

Electronic Control

Circuit

Opening/closing speed can be changed on site.

Heater with Temperature Sensor **Contributing to Energy Saving**

A typical countermeasure for cold environment is a heater working on for 24 hours/365 days, which inevitablly wastes energy to some extent. The PRP is equipped with a temperature sensor attached to its stepping motor, and supplies current to the motor to heat it to maintain the internal

Rotary Motion PRP Series

PSN Series Common Specifications

: 4 - 20 mA or 1 - 5 V DC Input signal

: 100 - 120 V AC (Not selectable for CE) 200 - 240 V Power input

Degree of protection: IP66

Wiring conduits : G 1/2 female thread (two)

Stepping motor

Available Manual

Position output: 4 - 20 mA DC

: -20 to +55°C (-4 to +131°F) (Standard models) 5 to 70°C (41 to +158°F) (Lloyd's Register approved) Operating

Vibration: Passed test condition below

· Acceleration: 2 G (19.6 m/s2) (Standard models)

: Potentiometer 0.7 G (6.9 m/s²) (Lloyd's Register approved) External View Model No. PRP-1x (€ IP66 (*) PRP-0x (€ IP66 €) Standard models -----Model No Llovd's Register PRP-0xx-x/LR PRP-1xx-x/LR approved (Environmental categories ENV3) Operational Angle 100 N·m 200 N·m Operation Time (90° 12 sec. (PRP-01) 24 sec. (PRP-03) 8.5 - 125 sec. (PRP-00) 16 sec. (PRP-11) 24 sec. (PRP-13) 16 - 125 sec. (PRP-10) 10.8 kg (23.8 lb) Approx. Weight Resolution 1/200 with 0.5 % deadband (factory setting); 1/1000 with 0.1 % deadband POSITION INDICATOR External Dimensions (Unit: mm [inch])

Rotary Motion Electric Actuators

Programming Unit

EAR Series

Accessory



Insulation class B (130°C)

Model: PSN-BAT

Mode: PU-2A

AC reversible motor enhances reliability

Suitable for outdoor environment

IP66 degree of protection

Resistant to vibration

Normal operation confirmed in vibration testing

* Refer to data sheet for external dimensions

Input signal Power supply voltage

: 4 - 20 mA or 1 - 5 V DC : 100 V AC±10% 200 V AC±10%

Position detection : Potentiometer (conductive plastic)

Manual operation : Available :-10 to +60°C (14 to 140°F) Operating temperature

Sweep endurance test condition (IEC 61298-3 compliant)

· Acceleration: 19.6 m/s² (2 G)

· 70 N·m Torque

: 90° (direct and reverse rotation)

: 4.7 kg (10.4 lb) Approx. weight Linearr resolution : 1/200

EAR70 **EAR Series**

Series

MSP10

PSN

Positioners MEX Series

Manual Loading

www.mgco.jp

MEX Series

Rotary Motion Electric Actuator

ROTARY MOTION

PRP-2

High torque 600 N⋅m and high resolution 1/1000

High torque 600 N·m

Planetary gear mechanism for speed reduction realizes the high torque of 600 N·m despite its compact size.

Long Life and High Precision

Stepping motor drive realizes long life and high precision

Manual Handle Locked During Motor Operation

The worm gear for manual operation is locked to prevent the manual handle from turning during normal operation.

Open network interface









Transparent image of PRP-2





Endurable

Mechanism

Output Stem

Gear

MSP10

MEX Series

Loading

Planetary Gear Mechanism



A planetary gear mechanism consists of two gears (the "planet") revolving around the center of the other (the "sun"), just like the planets revolve around the sun. A planetary carrier connects to the centers of the two planetary gears and rotates, to rotate the output shaft of the mechanism in turn.

The planetary gear mechanism can yield higher torque with a smaller number of gears compared from that required by a combination of spur gears, resulting in compact size and small

Stepping Motor



The drive section employs a stepping motor featuring no mechanical contact structure and long life. The minimum rotating angle of the motor is 1.8 degrees per pulse, enabling high accuracy opening control.

Endurable Gear Mechanism



Dry bearings needing no lubrication are employed to balance robustness of the bearings and high reliability/

Thermal Control



is separated from the other electronic circuits. The heat dissipation efficiency of the board itself is also improved.

Potentiometer for Position Detection



used for industrial vehicles or construction machines is used to realize vibration resistance, high quality and long life.



The class of potentiometer typically

Rotary Motion PRP-2

Main Specifications

: 4 - 20 mA or 1 - 5 V DC

Power input : 100 - 120 V AC or 200 - 240 V AC

Degree of protection: IP66

Wiring conduits : G 1/2 female thread (two)

Drive : Stepping motor

Position detection : Potentiometer (conductive plastic type) Position output : 4 - 20 mA DC

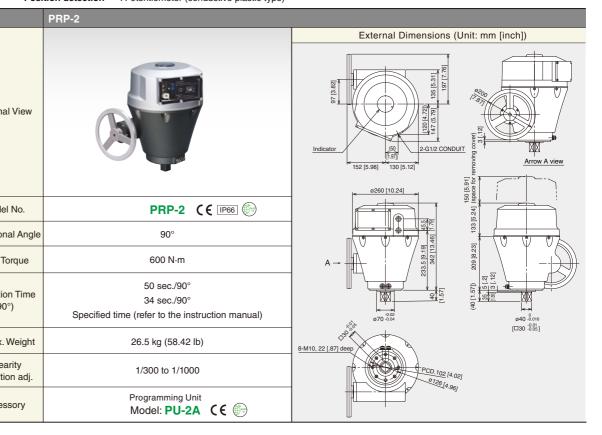
Operating temperature : -20 to +55°C (-4 to +131°F)

Vibration: Passed test condition below

(Fixed frequency endurance test, Sweep endurance test)

· Acceleration: 2 G (19.6 m/s²)





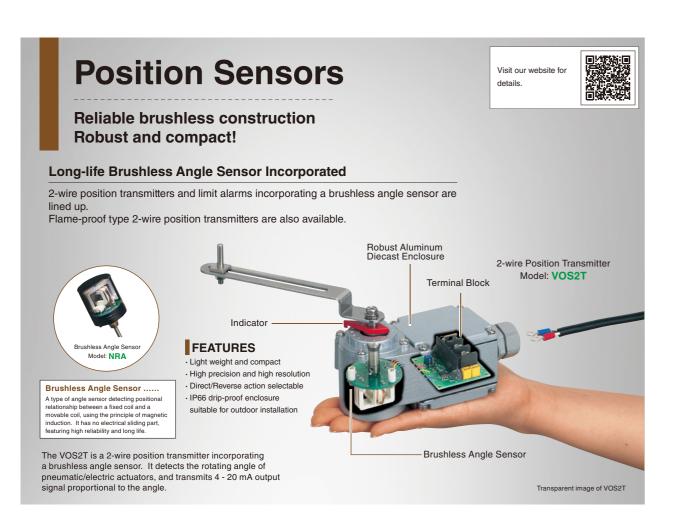
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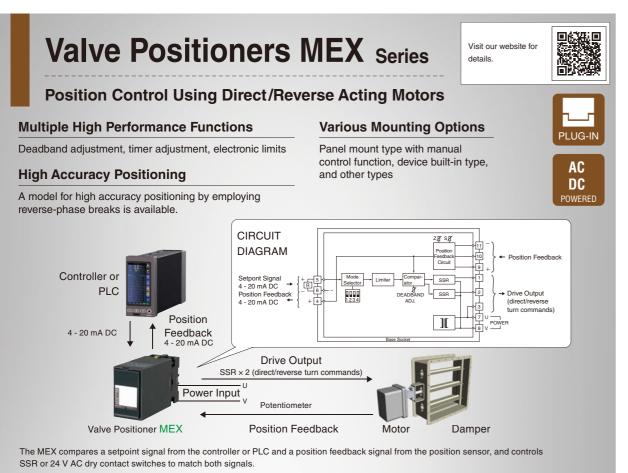
Positioners

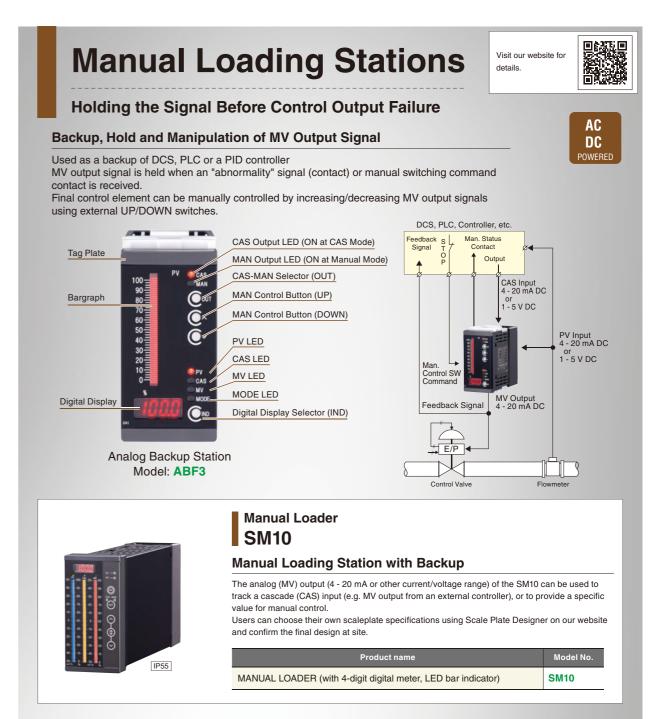
MEX Series

Manual

Series







MSP Series

MSP Series

MSP10

PSN Series

> MRP Series

MRP10

PRP

Series

Position

Valve Positioners MEX Series

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